#### Astro 448

# Set 2: Theoretical Data Analysis Wayne Hu

#### Time Ordered Data

- Beyond idealizations like  $|\Theta_{\ell m}|^2$  type  $C_{\ell}$  estimators and  $f_{\rm sky}$  mode counting, basic aspects of data analysis are useful even for theorists
- Starting point is a string of "time ordered" data coming out of the instrument (post removal of systematic errors, data cuts)
- Begin with a model of the time ordered data as (implicit summation or matrix operation)

$$d_t = P_{ti}\Theta_i + n_t$$

where i denotes pixelized positions indexed by i,  $d_t$  is the data in a time ordered stream indexed by t e.g. number of time ordered data numbers up to  $10^{10}$  whereas number of pixels  $10^6 - 10^7$ .

• Noise  $n_t$  is drawn from distribution with known power spectrum

$$\langle n_t n_{t'} \rangle = C_{d,tt'}$$

## Design Matrix

- The design, pointing or projection matrix P is the mapping between pixel space and the time ordered data
- Simplest incarnation: row with all zeros except one column which just says what point in the sky the telescope is pointing at that time

$$\mathbf{P} = \begin{pmatrix} 0 & 0 & 1 & \dots & 0 \\ 1 & 0 & 0 & \dots & 0 \\ & & & & & \\ 0 & 0 & 1 & \dots & 0 \end{pmatrix}$$

- If each pixel were only measured once in this way then the estimator of the map would just be the inverse of **P**
- More generally encorporates differencing, beam, rotation (for polarization) and unequal coverage of pixels

## Maximum Likelihood Mapmaking

- What is the best estimator of the underlying map  $\Theta_i$ ?
- Likelihood function: the probability of getting the data given the theory  $\mathcal{L} \equiv P[\text{data}|\text{theory}]$ . In this case, the *theory* is the set of parameters  $\Theta_i$ .

$$\mathcal{L}_{\Theta}(d_t) = \frac{1}{(2\pi)^{N_t/2} \sqrt{\det \mathbf{C}_d}} \exp \left[ -\frac{1}{2} \left( d_t - P_{ti} \Theta_i \right) C_{d,tt'}^{-1} \left( d_{t'} - P_{t'j} \Theta_j \right) \right].$$

• Bayes theorem says that  $P[\Theta_i|d_t]$ , the probability that the temperatures are equal to  $\Theta_i$  given the data, is proportional to the likelihood function times a  $prior\ P(\Theta_i)$ , taken to be uniform

$$P[\Theta_i|d_t] \propto P[d_t|\Theta_i] \equiv \mathcal{L}_{\Theta}(d_t)$$

## Maximum Likelihood Mapmaking

- Maximizing the likelihood of  $\Theta_i$  is simple since the log-likelihood is quadratic.
- Differentiating the argument of the exponential with respect to  $\Theta_i$  and setting to zero leads immediately to the estimator

$$\hat{\Theta}_i = C_{N,ij} P_{jt} C_{d,tt'}^{-1} d_{t'} ,$$

where  $\mathbf{C}_N \equiv (\mathbf{P}^{\mathrm{tr}}\mathbf{C}_d^{-1}\mathbf{P})^{-1}$  is the covariance of the estimator

• Given the large dimension of the time ordered data, direct matrix manipulation is unfeasible. A key simplifying assumption is the stationarity of the noise, that  $C_{d,tt'}$  depends only on t-t' (temporal statistical homogeneity)

#### Foregrounds

- Maximum likelihood mapmaking can be applied to the time streams of multiple observations frequencies  $N_{\nu}$  and hence obtain multiple maps
- A cleaned CMB map can be obtained by modeling the maps as

$$\hat{\Theta}_i^{\nu} = A_i^{\nu} \Theta_i + n_i^{\nu} + f_i^{\nu}$$

where  $A_i^{\nu}=1$  if all the maps are at the same resolution (otherwise, embed the beam as in the pointing matrix;  $f_i^{\nu}$  is the noise contributed by the foregrounds

- Again, a map making problem. Given a covariance matrix for foregrounds noise (a prior from other data), same solution.
   Alternately, can derive weights from stats of the recovered maps
- 5 foregrounds: synchrotron, free-free, radio pt sources, at low frequencies and dust and IR pt sources at high frequencies.

#### Power Spectrum

• The next step in the chain of inference is the power spectrum extraction. Here the correlation between pixels is modelled through the power spectrum

$$C_{S,ij} \equiv \langle \Theta_i \Theta_j \rangle = \sum_{\ell} \frac{\ell(\ell+1)C_{\ell}}{2\pi} W_{\ell,ij}$$

- $W_{\ell}$ , the window function, is derived by writing down the expansion of  $\Theta(\hat{\mathbf{n}})$  in harmonic space, including smoothing by the beam and pixelization
- For example in the simple case of a gaussian beam of width  $\sigma$  it is proportional to the Legendre polynomial  $P_{\ell}(\hat{\mathbf{n}}_i \cdot \hat{\mathbf{n}}_j)$  for the pixel separation multiplied by  $b_{\ell}^2 \propto e^{-\ell(\ell+1)\sigma^2}$

## Bandpowers

- In principle the underlying theory to extract from pixel data is the power spectrum at every  $\ell$
- However with a finite patch of sky, multipoles separated by  $\Delta \ell < 2\pi/L$  where L is the dimension of the survey will fully-covary and not supply independent information
- So consider instead a theory parameterization of  $\ell(\ell+1)C_{\ell}/2\pi$  constant in bands of  $\Delta\ell$  chosen to match the survey forming a set of bandpowers  $B_a$
- The likelihood of the bandpowers given the pixelized data is

$$\mathcal{L}_B(\Theta_i) = \frac{1}{(2\pi)^{N_p/2} \sqrt{\det \mathbf{C}_{\Theta}}} \exp\left(-\frac{1}{2}\Theta_i C_{\Theta,ij}^{-1} \Theta_j\right)$$

where  $C_{\Theta} = C_S + C_N$  and  $N_p$  is the number of pixels in the map.

#### Bandpower Estmation

- As before,  $\mathcal{L}_B$  is Gaussian in the anisotropies  $\Theta_i$ , but in this case  $\Theta_i$  are *not* the parameters to be determined; the theoretical parameters are the  $B_a$ , upon which the covariance matrix depends.
- The likelihood function is not Gaussian in the parameters, and there is no simple, analytic way to find the maximum likelihood bandpowers or their covariance
- In principle one can still use Bayes' Theorem to find the posterior joint probability of the bandpowers or the cosmological parameters that parameterize them
- In practice the exact likelihood is expensive to compute
- Need fast approximation to the likelihood function and a fast way of exploring it

## Bandpower Estmation

- One example is to find the maximum likelihood bandpowers by iteration
- Take a trial point  $B_a^{(0)}$  and improve estimate based a Newton-Rhapson approach to finding zeros

$$\hat{B}_{a} = \hat{B}_{a}^{(0)} + \hat{F}_{B,ab}^{-1} \frac{\partial \ln \mathcal{L}_{B}}{\partial B_{b}}$$

$$= \hat{B}_{a}^{(0)} + \frac{1}{2} \hat{F}_{B,ab}^{-1} \left( \Theta_{i} C_{\Theta,ij}^{-1} \frac{\partial C_{\Theta,jk}}{\partial B_{b}} C_{\Theta,kl}^{-1} \Theta_{l} - C_{\Theta,ij}^{-1} \frac{\partial C_{\Theta,ji}}{\partial B_{b}} \right) ,$$

Still need the covariance matrix of the bandpowers

#### Fisher Matrix

• The expectation value of the local curvature is the Fisher matrix

$$F_{B,ab} \equiv \left\langle -\frac{\partial^2 \ln \mathcal{L}_B}{\partial B_a \partial B_b} \right\rangle$$

$$= \frac{1}{2} C_{\Theta,ij}^{-1} \frac{\partial C_{\Theta,jk}}{\partial B_a} C_{\Theta,kl}^{-1} \frac{\partial C_{\Theta,li}}{\partial B_b}.$$

• This is a general statement: for a gaussian distribution the Fisher matrix

$$F_{ab} = \frac{1}{2} \text{Tr}[\mathbf{C}^{-1} \mathbf{C}_{,a} \mathbf{C}^{-1} \mathbf{C}_{,b}]$$

- Kramer-Rao identity says that the best possible covariance matrix on a set of parameters is  ${\bf C}={\bf F}^{-1}$
- Thus, the iteration returns an estimate of the covariance matrix of the estimators  $C_B$

## Cosmological Parameters

• The probability distribution of the bandpowers given the cosmological parameters  $c_i$  is not Gaussian but central limit theorem says at high  $\ell$  it is often an adequate approximation

$$\mathcal{L}_c(\hat{B}_a) \approx \frac{1}{(2\pi)^{N_c/2} \sqrt{\det \mathbf{C}_B}} \exp \left[ -\frac{1}{2} (\hat{B}_a - B_a) C_{B,ab}^{-1} (\hat{B}_b - B_b) \right]$$

- Again Bayes' theorem gives the joint posterior of the cosmological parameters from the bandpower likelihood
- With this or other more sophisticated approximations to the bandpower likelihood, still need a fast approach to exploring the bandpower likelihood function

#### **MCMC**

- Monte Carlo Markov Chain (MCMC)
- Start with a set of cosmological parameters  $c^m$ , compute likelihood
- Take a random step in parameter space to  $\mathbf{c}^{m+1}$  of size drawn from a multivariate Gaussian (a guess at the parameter covariance matrix)  $\mathbf{C}_c$  (e.g. from the crude Fisher approximation or the covariance of a previous short chain run). Compute likelihood.
- Draw a random number between 0,1 and if the likelihood ratio exceeds this value take the step (add to Markov chain); if not then do not take the step (add the original point to the Markov chain). Repeat.
- Given Bayes' theorem the chain is then a sampling of the joint posterior probability density of the parameters

#### Parameter Errors

- Can compute any statistic based on the probability distribution of parameters
- For example, compute the mean and variance of a given parameter

$$\bar{c}_i = \frac{1}{N_M} \sum_{m=1}^{N_M} c_i^m$$

$$\sigma^{2}(c_{i}) = \frac{1}{N_{M} - 1} \sum_{m=1}^{N_{M}} (c_{i}^{m} - \bar{c}_{i})^{2}$$

- Trick is in assuring burn in (not sensitive to initial point), step size, and convergence
- Usually requires running multiple chains. Typically tens of thousands of elements per chain.

## Radical Compression

- Started with time ordered data  $\sim 10^{10}$  numbers for a satellite experiment
- Compressed to a map assuming a CMB spectrum (and time independent fluctuations)  $\sim 10^7$  numbers
- Compressed to a power spectrum (Gaussian statistics) independent of m (statistical isotropy)  $\sim 10^3$  numbers
- Compressed to cosmological parameters (a cosmological model)  $\sim 10^3$
- A factor of 10<sup>9</sup> reduction in the representation. Nature is very efficient.

#### Parameter Forecasts

- Now connect this discussion with the crude approximations from previous set of notes.
- Gaussian approximation says Fisher matrix of the cosmological parameters becomes

$$F_{c,ij} = \frac{\partial B_a}{\partial c_i} C_{B,ab}^{-1} \frac{\partial B_b}{\partial c_j}$$

which is the error propagation formula discussed above

- The bandpower covariance can be computed from the Fisher approximation of the pixel likelihood.
- In the crude approximation one takes the covariance to be given by the number of independent modes going into each bandpower estimate

#### Parameter Forecasts

• For bandpowers being  $C_{\ell}$  itself, i.e. estimating every  $\ell$  approximate covariance with an increased variance:

$$F_{ij} = \sum_{\ell} \frac{(2\ell+1)f_{\text{sky}}}{2(C_{\ell}^{\Theta\Theta} + C_{\ell}^{NN})^2} \frac{\partial C_{\ell}^{\Theta\Theta}}{\partial c_i} \frac{\partial C_{\ell}^{\Theta\Theta}}{\partial c_j}$$

where the sky fraction  $f_{\rm sky}$  quantifies the loss of independent modes due to the sky cut

• This is the form we previously derived from just thinking about the simple estimator